

Controller Area Network Projects Lesbonsites

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RIVAS ROGERS

A Comprehensible Guide to Controller Area Network Copperhill Media
Controller Area Network (CAN) is a serial network technology that was originally designed for the automotive industry, but has also become a popular bus in industrial automation. The CAN bus is primarily used in embedded solutions and provides communication among microprocessors up to real-time requirements. A Comprehensible Guide To Controller Area Network represents a very thoroughly researched and complete work on CAN. It provides information on all CAN features and aspects combined with high level of readability. Book jacket.
Controller Area Network Projects
The Controller Area Network (CAN) was originally developed to be used as a vehicle data bus system in passenger cars.

Today, CAN controllers are available from over 20 manufacturers, and CAN is finding applications in other fields, such as medical, aerospace, process control, automation, and so on. This book is written for students, for practising engineers, for hobbyists, and for everyone else who may be interested to learn more about the CAN bus and its applications. The aim of this book is to teach you the basic principles of CAN networks and in addition the development of microcontroller based projects using the CAN bus. In summary, this book enables the reader to: Learn the theory of the CAN bus used in automotive industry; Learn the principles, operation, and programming of microcontrollers; Design complete microcontroller based projects using the C language; Develop complete real CAN bus projects using microcontrollers; Learn the principles of OBD systems used to debug vehicle electronics. You will learn how to design microcontroller based CAN bus nodes, build a CAN bus, develop high-level

programs, and then exchange data in real-time over the bus. You will also learn how to build microcontroller hardware and interface it to LEDs, LCDs, and A/D converters. The book assumes that the reader has some knowledge on basic electronics. Knowledge of the C programming language will be useful in later chapters of the book, and familiarity with at least one member of the PIC series of microcontrollers will be an advantage, especially if the reader intends to develop microcontroller based projects using the CAN bus. The CD contains a special demo version of the mikroC compiler which supports the key microcontrollers including: PIC, dsPIC, PIC24, PIC32 and AVR. This special version additionally features an advanced CAN library of intuitive and simple-to-use functions to encourage programming with easy and comfortable development of CAN networks.

Controller Area Network